

# ABS ABS Driver

|                            |                            |
|----------------------------|----------------------------|
| <b>File Name</b>           | ABS.dll                    |
| <b>Manufacturer</b>        | ABS Telemetria             |
| <b>Devices</b>             | ABS Modems and Dataloggers |
| <b>Protocol</b>            | Modbus                     |
| <b>Version</b>             | 1.0.3                      |
| <b>Last Update</b>         | 09/04/2025                 |
| <b>Platform</b>            | Win32                      |
| <b>Dependencies</b>        | IOKit version 2.0 or later |
| <b>Superblock Readings</b> | No                         |
| <b>Level</b>               | 31301                      |

## Introduction

This Driver implements communication with modems and dataloggers by ABS Telemetria based on Modbus protocol.

## Preparing a Device

A device must be configured to start connecting to this Driver, and users must configure the next parameters:

- **Host Address/Port:** IP address and TCP/IP port that a device uses to connect. The IP address must be the one from the computer of this Driver, and the TCP/IP port must be the same one configured in this Driver in the **Listen Port** option on the **Ethernet** tab
- **Host Type:** Must be equal to 2 (two)
- **Host Login:** Code with 8 (eight) characters send as soon as a device connects to the IP address and TCP/IP port informed. This very code must be informed in the ABS.ini file. For more information, please check topic **Driver Configuration**

### NOTE

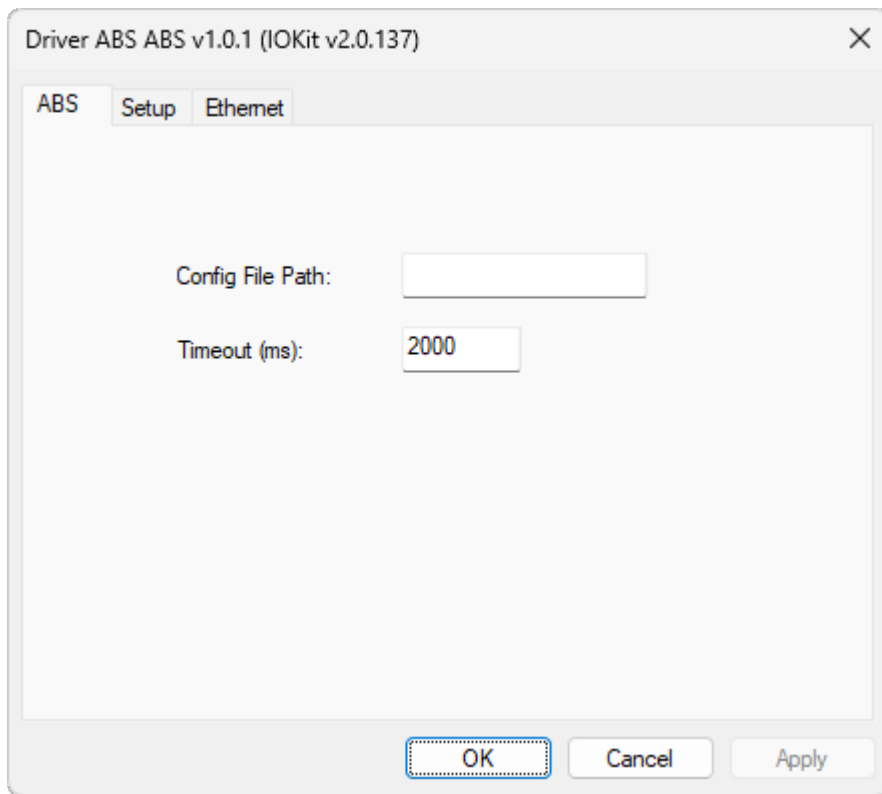
Some products support several connections with a different identifier for each one of these connections, and in this case please contact ABS's *technical support*.

## Driver Configuration

This Driver's **[P]** parameters are not used. All configurations are performed on this Driver's configuration dialog box. For more information about the configuration tabs, please check topic **Documentation of I/O Interfaces**.

## Configuring Properties

The configurations of this Driver are performed on the **ABS** tab, shown on the next figure.



**ABS tab**

The available options on this tab are described on the next table.

**Available options on the ABS tab**

| OPTION                  | DESCRIPTION  |
|-------------------------|--|
| <b>Config File Path</b> | Folder to which are saved the configuration or device identification file, the ABS.ini file, and the reading pointer file of the Datalogger of each device, the ABSLoggerPointers.ini file |
| <b>Timeout (ms)</b>     | Maximum time to wait, in milliseconds, for a reading or writing operation to be considered in failure  |

**ABS.ini File**

On the folder informed in the **Config File Path** option, users must create a file, in **Text** format, with the identification and configuration of modems, so that this Driver refuse connections from modems not registered. This file must be named ABS.ini, and each line must contain the definition of a device, in the format **ID;DeviceAddress;Protocol**, in which:

- **ID**: A decimal number identifying a modem, used in Tags as the address of that modem
- **DeviceAddress**: Unique code of a device, a value with 8 (eight) characters in hexadecimal format, configured in a device in the **Host Login** property
- **Protocol**: Communication protocol. Possible values are **TCP**, **RTU**, or **ASC**

The next code contains an example of this file.

```
1;0B230ACC;TCP
2;0B230ACD;TCP
```

## ABSLoggerPointers.ini File

This file is automatically generated when stopping the execution of this Driver, containing a line for each device, in the format **ID;SavePointer;CurrentLoggerBlock**, in which:

- **ID**: A decimal number identifying a modem, defined in the ABS.ini file
- **SavePointer**: Indicates whether users want to save a Logger's pointer. Possible values are 0 (zero) or 1 (one). This value is defined in the **N4** parameter of the Block Tag for Reading Events
- **CurrentLoggerBlock**: Position or address of the last reading of the stack of events of a Logger

All offline properties must be configured using PLC Tags in **String** format using the *N1* parameter equal to -1 (minus one), the *N2* parameter equal to 0 (zero), the *N3* parameter equal to 0 (zero), and the *N4* parameter equal to 3 (three). For more details and examples, please check topic **Documentation of I/O Interfaces**.

## Tag Reference

Tags are configured using the **Device** and **Item** properties and the *N2* and *N4* parameters.

- **Device**: Indicates the address of a device as defined in the **ABS.ini** file, followed by a colon (:), such as **1:**. The Modbus address is fixed in 0 (zero)
- **N2**: Indicates the type of a Tag. Possible values are described on the next table

**Possible values for the N2 parameter**

| N2   | NAME                      | DESCRIPTION   |
|------|---------------------------|---|
| 0    | User Tags                 | Normal Tags with real-time readings and writings, according to the address defined in the <b>Item</b> parameter   |
| 9999 | State                     | Indicates whether a device is in active communication. Possible values are 0 (zero, inactive) or 1 (one, active)  |
| 100  | Event Reading (Block Tag) | Users must create a Block Tag with a Block Element for each channel configured in a Logger. Each analog channel occupies a Block Element, and if a Logger is also configured to store digital inputs and outputs, they occupy the first 2 (two) Block Elements, and the next Block Elements correspond to each one of the other analog channels configured. The timestamp of each record is returned in the <b>TimeStamp</b> property of this Block Tag. To process each one of the records returned in this Block Tag, such as for storing on a Historic object, users must use a script on the <b>OnTagRead</b> event of this Block Tag |

- **N4**: Used only for the Event Reading Block Tag, with the *N2* parameter equal to 100, informing the type of management of a Logger. Possible values are **0**: Does not save the pointer from the last reading when stopping this

Driver, **1**: Saves the pointer from the last reading when stopping this Driver, or **2**: Deletes events after reading, and therefore does not save the pointer from the last reading when stopping this Driver because there is no need to store it

- **Item**: If the *N2* parameter is equal to 0 (zero, Users Tags), inform the address and operation to perform by this Tag, with the following syntax:

```
<addressing space><address>[.<type>[<size of type>]][.<byte order>][bit]
```

#### Available options for the Addressing Space parameter

| ADDRESSING SPACE               | MNEMONIC | NATIVE DATA TYPE   | FUNCTION  | COMMENTS   |
|--------------------------------|----------|--------------------|---|--|
| <b>Holding Register</b>        | hr       | 16-bit <b>Word</b> | Functions <b>03</b> and <b>16</b>               | Functions <b>03</b> and <b>16</b> are the most used of Modbus class 0 (zero) protocol  |
| <b>Single Holding Register</b> | shr      | 16-bit <b>Word</b> | Functions <b>03</b> and <b>06</b>               | Function <b>06</b> writes to the same registers of function <b>16</b> , the difference is that function <b>16</b> can write to Block Tags, while function <b>06</b> writes to one register at a time, but with less overhead |
| <b>Coil</b>                    | cl       | <b>Bit</b>         | Functions <b>01</b> and <b>15</b>               |  |
| <b>Single Coil</b>             | scl      | <b>Bit</b>         | Functions <b>01</b> and <b>05</b>               | Function <b>05</b> writes to the same registers of function <b>15</b> , but it cannot write to Block Tags, therefore with less overhead  |
| <b>Discrete Input</b>          | di       | <b>Bit</b>         | Functions <b>02</b> and <b>None</b> (read-only) |  |
| <b>Input Register</b>          | ir       | 16-bit <b>Word</b> | Functions <b>04</b> and <b>None</b> (read-only) |  |
| <b>Exception Status</b>        | es       | <b>Byte</b>        | Functions <b>07</b> and <b>None</b> (read-only) |  |
| <b>File Register</b>           | fr       | 16-bit <b>Word</b> | Functions <b>20</b> and <b>21</b>               |  |

The **Address** parameter is a number identifying the address of an item, register or bit, to read or write inside the defined addressing space. Values can be provided in decimal, hexadecimal, or octal format. For values in decimal, there is no need to add a prefix, or users can use the **&d** prefix. For values in hexadecimal, add the **&h** prefix, such as **&hFFFF**. For the octal format, use the **&o** prefix, such as **&o843**. This address may have an offset, relative to the address actually sent in a communication frame, which depends on the convention used by the manufacturer.

The parameters described next, on the other hand, are optional and used for extension to the default protocol or for compatibility with devices not fully adherent to protocol, also detailed later.

The **Type** parameter defines how bytes of a data area of a communication frame must be interpreted. If omitted, the default data types defined by the protocol are used for the functions in use, that is, **Word** for functions to access registers and **Bit** for functions to access digital data, Coils and Discrete Inputs.

### Supported data types

| DATA TYPE      | MNEMONIC | ALIAS    |
|----------------|----------|----------|
| Char           | char     | ch       |
| Byte           | byte     | by or u8 |
| Int8           | int8     | i8       |
| Int16          | int16    | i16      |
| Int32          | int32    | i32      |
| Word or UInt   | word     | u16      |
| DWord or ULong | dword    | u32      |
| Float          | float    | f        |
| Float_GE       | float_GE | fge      |
| Double or Real | double   | d        |
| String         | string   | s        |

The **Size of type** parameter is only necessary to specify for data types with variable size, such as **BCD** and **String**. The value of this parameter indicates the size of a data type, in bytes.

The **Byte order** parameter is a mnemonic indicating the order of bytes for number values. If this parameter is omitted, the protocol default is used, with the most significant bytes first in the communication frame, which is equivalent to **b0**, called *Big Endian*. The next table indicates which swap operations, that is, Swap Bytes, Swap Words, and Swap DWords, are performed for each sorting mnemonic, from **b0** to **b7**.

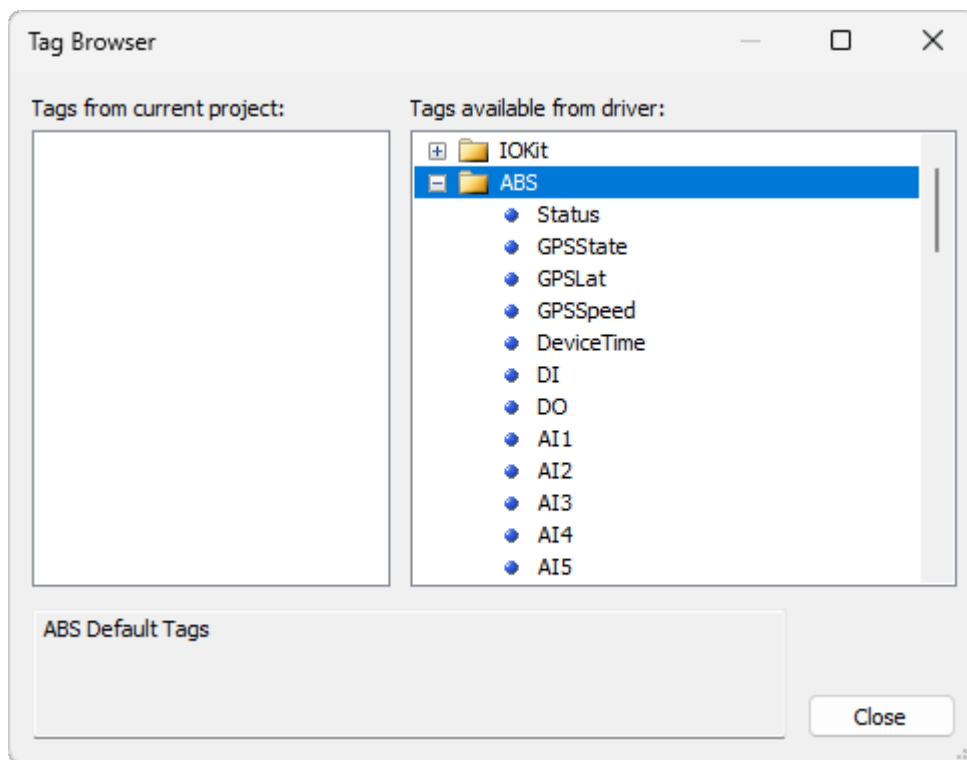
### Swapping operations

|           | SWAP BYTES | SWAP WORDS | SWAP DWORDS | ALIAS | ALIAS 2 (SWAPS) | SORTING                               |
|-----------|------------|------------|-------------|-------|-----------------|---------------------------------------|
| <b>b0</b> |            |            |             | msb   | -               | by7 by6 by5<br>by4 by3 by2<br>by1 by0 |
| <b>b1</b> | X          |            |             | -     | sb              | by6 by7 by4<br>by5 by2 by3<br>by0 by1 |
| <b>b2</b> |            | X          |             | -     | sw              | by5 by4 by7<br>by6 by1 by0<br>by3 by2 |
| <b>b3</b> | X          | X          |             | -     | sb.sw           | by4 by5 by6<br>by7 by0 by1<br>by2 by3 |
| <b>b4</b> |            |            | X           | -     | sdw             | by3 by2 by1<br>by0 by7 by6<br>by5 by4 |
| <b>b5</b> | X          |            | X           | -     | sb.sdw          | by2 by3 by0<br>by1 by6 by7<br>by4 by5 |
| <b>b6</b> |            | X          | X           | -     | sw.sdw          | by1 by0 by3<br>by2 by5 by4            |

|           | SWAP BYTES | SWAP WORDS | SWAP DWORDS | ALIAS | ALIAS 2 (SWAPS) | SORTING                               |
|-----------|------------|------------|-------------|-------|-----------------|---------------------------------------|
|           |            |            |             |       |                 | by7 by6                               |
| <b>b7</b> | X          | X          | X           | lsb   | sb.sw.sdw       | by0 by1 by2<br>by3 by4 by5<br>by6 by7 |

The **Bit** parameter allows returning a specific bit of an integer value, and it is obviously needed only in Modbus functions that return integer values, or **Words**. Usually, it is recommended to no use that feature, prefer an application's bit mapping. Bit 1 (one) is the least significant and, the greater the value, the more significant is that bit. The maximum allowed value obviously depends on the size of the data type, and it is currently 64 for **Double** data types. This parameter corresponds to the old **Use Bit Mask** option of number configuration.

When opening Tag Browser window, the main Tags offered by a device are already available, according to the next figure.



Tag Browser window

## Documentation of I/O Interfaces

This section contains the documentation of I/O Interfaces referring to **ABS** Driver.

## Configuration of a Driver

I/O Interface configuration is performed on a Driver's configuration dialog box. To access the configuration of this dialog box in **Elipse E3** in version 1.0, follow these steps:

1. Right-click a Driver object (IODriver).
2. Select the **Properties** item on the contextual menu.
3. Select the **Driver** tab.
4. Click **Other parameters**.

In **Elipse E3** version 2.0 or later, click **Configure driver**  on a Driver's toolbar. In **Elipse SCADA**, follow these steps:

1. Open the Organizer.
2. Select a Driver on Organizer's tree.
3. Click **Extras** on the **Driver** tab.

Currently, an I/O Interface allows opening only one connection for each Driver. This means that, if users want to access two serial ports, they must add two Drivers to an application and then configure each one of these Drivers for each serial port.

## Configuration Dialog Box

The dialog box of I/O Interfaces allows configuring the I/O connection used by a Driver. This dialog box contains the **Setup**, **Serial**, **Ethernet**, **Modem**, and **RAS** tabs, described on the next topics. If a Driver does not implement a specific I/O connection, its corresponding tab is not available for configuration. Some Drivers may contain additional tabs, specific for that Driver, on the configuration dialog box.

## Setup Tab

The **Setup** tab contains general configurations of a Driver. This tab is divided into the following groups:

- **General configurations:** Configurations of a Driver's physical layer, time-out, and initialization mode
- **Connection management:** Configurations on how the I/O Interface keeps a connection and which recovery policy is used on failure
- **Logging options:** Controls the generation of log files

Setup

Physical Layer: Ethernet  Start driver OFFLINE

Timeout: 1000 ms      Communication check time: 5000 ms

Connection management

Mode: Automatic (managed by the driver)

Retry failed connection every 20 seconds

Give up after 1 failed retries

Disconnect if non-responsive for 0 seconds

Logging Options

Log to File: C:\eeLogs\MicrolokII\_%DATE%.log

File size limit (MB): 0 ('0' is unlimited)

**Setup tab**

**General options on the Setup tab**

| OPTION                          | DESCRIPTION   |
|---------------------------------|---|
| <b>Physical Layer</b>           | Select the physical layer on a list. Available options are <b>Serial</b> , <b>Ethernet</b> , <b>Modem</b> , and <b>RAS</b> . The selected interface must be configured on its specific tab  |
| <b>Timeout</b>                  | Configure a time-out, in milliseconds, for the physical layer. This is the amount of time an I/O interface waits to receive any byte from the reception's buffer  |
| <b>Communication check time</b> | Set the time, in milliseconds, to define the interval at which communication is considered to be in an inactive state. As long as an I/O Driver receives valid data, its communication state is considered active. However, if during operation an I/O Driver does not receive valid data inside this period of time, the state is considered inactive. The communication state is shown in the <b>IO.CommunicationStatus</b> Tag |
| <b>Start driver OFFLINE</b>     | Select this option so that a Driver starts in <b>Offline</b> mode or stopped. This means that the I/O interface is not created until this Driver is configured to <b>Online</b> mode by using a Tag in an application. This mode enables a dynamic configuration of an I/O interface at run time  |

## Options on the Connection management group

| OPTION  | DESCRIPTION   |
|---|---|
| <b>Mode</b>   | Selects a management mode of a connection. Selecting the <b>Automatic</b> option allows a Driver to manage the connection automatically, as specified in the next options. Selecting the <b>Manual</b> option allows an application to fully manage a connection  |
| <b>Retry failed connection every ... seconds</b>    | Select this option to enable a Driver's connection retry in a certain interval, in seconds. If the <b>Give up after failed retries</b> option is not selected, this Driver keeps retrying until a connection is performed, or until the application is stopped  |
| <b>Give up after ... failed retries</b>             | Enable this option to define a maximum number of connection retries. When the specified number of consecutive connection retries is reached, a Driver goes to the <b>Offline</b> mode, assuming that a hardware problem was detected. If a Driver establishes a successful connection, the number of unsuccessful retries is cleared. If this new connection is lost, then the retry counter starts at zero |
| <b>Disconnect if non-responsive for ... seconds</b> | Enable this option to force a Driver to disconnect if no byte was received by the I/O interface during the specified time-out, in seconds. This time-out must be greater than the time-out configured in the <b>Timeout</b> option  |

## Options on the Logging Options group

| OPTION                      | DESCRIPTION   |
|-----------------------------|---|
| <b>Log to File</b>          | <p>Enable this option and configure the name of a file to write a log. Log files can be large, so use this option for short periods of time, only for testing and debugging purposes. If the <b>%PROCESS%</b> macro is used in the log file name, it is replaced by the identifier of the current process. This option is particularly useful when using several instances of the same Driver in <b>Elipse E3</b>, thus allowing each instance to generate a separate log file. For example, when configuring this option with value "c:\e3logs\drivers\sim_%PROCESS%.log", it generates a file named c:\e3logs\drivers\sim_00000FDA.log for process <b>OFDAh</b>. Users can also use the <b>%DATE%</b> macro in the file name. In this case a log file is generated every day, in the format <b>aaaa_mm_dd</b>. For example, when configuring this option with value "c:\e3logs\drivers\sim_%DATE%.log", it generates a file named c:\e3logs\drivers\sim_2005_12_31.log in 12/31/2005 and a file named c:\e3logs\drivers\sim_2006_01_01.log in 01/01/2006. Similarly, the <b>%DATE_HOUR%</b> macro generates one log file per hour, in the format <b>aaaa_mm_dd_hh</b></p> |
| <b>File size limit (MB)</b> | <p>Configure the log file size limit, in megabytes. A value equal to 0 (zero) means that there is no size limit for the log file</p>  |

## Ethernet Tab

Use this tab to configure parameters of an **Ethernet** Interface. These parameters, except port configurations, must also be configured for use in the **RAS** Interface.

Ethernet

Transport: TCP/IP ▼

PING before connecting

Timeout: 4000 ms

Retries: 1

Listen for connections on port: 0

Share listen port with other processes

Interface: (All Interfaces) ▼

Use IPv6  Use SSL SSL Settings

Enable 'ECHO' supression

IP Filter:

Connect to

|                                       |  |       |  |                                      |  |
|---------------------------------------|--|-------|--|--------------------------------------|--|
| <input type="checkbox"/> Main IP:     | <span style="border: 1px solid gray; padding: 2px;"> </span> | Port: | <span style="border: 1px solid gray; padding: 2px;">502</span> | <input type="checkbox"/> Local port: | <span style="border: 1px solid gray; padding: 2px;">0</span> |
| <input type="checkbox"/> Backup IP 1: | <span style="border: 1px solid gray; padding: 2px;"> </span> | Port: | <span style="border: 1px solid gray; padding: 2px;">0</span>   | <input type="checkbox"/> Local port: | <span style="border: 1px solid gray; padding: 2px;">0</span> |
| <input type="checkbox"/> Backup IP 2: | <span style="border: 1px solid gray; padding: 2px;"> </span> | Port: | <span style="border: 1px solid gray; padding: 2px;">0</span>   | <input type="checkbox"/> Local port: | <span style="border: 1px solid gray; padding: 2px;">0</span> |
| <input type="checkbox"/> Backup IP 3: | <span style="border: 1px solid gray; padding: 2px;"> </span> | Port: | <span style="border: 1px solid gray; padding: 2px;">0</span>   | <input type="checkbox"/> Local port: | <span style="border: 1px solid gray; padding: 2px;">0</span> |

**Ethernet tab**

**Available options on the Ethernet tab**

| OPTION  | DESCRIPTION   |
|---|---|
| <b>Transport</b>                              | Select the value <b>TCP/IP</b> for a TCP socket ( <i>stream</i> ) or select the value <b>UDP/IP</b> to use a UDP socket ( <i>connectionless datagram</i> )  |
| <b>Listen for connections on port</b>         | Use this option to wait for new connections in a specific IP port, common in Slave Drivers. If this option remains unselected, a Driver connects to the address and port specified in the <b>Connect to</b> option  |
| <b>Share listen port with other processes</b> | Select this option to share the listening port with other Drivers and processes   |
| <b>Interface</b>                              | Select the local network interface, identified by its IP address, that a Driver uses to establish and receive connections, or select the value <b>(All Interfaces)</b> to allow connection in any network interface |
| <b>Use IPv6</b>                               | Select this option to force a Driver to use addresses in <b>IPv6</b> format on all Ethernet connections. Leave this option deselected to use the <b>IPv4</b> format   |
| <b>Enable 'ECHO' supression</b>               | Enable this option to remove the echo from received data. An echo is a copy of sent data, which can be returned before a reply message  |
| <b>IP Filter</b>                              | List of restricted or allowed IP addresses from where a Driver accepts connections ( <i>Firewall</i> ). Please check the <b>IO.Ethernet.IPFilter</b> property for more information                                  |
| <b>PING before connecting</b>                 | Enable this option to execute a <b>ping</b> command, that is, to check whether a device can be reached on a network, for a device before trying a socket connection. This is a quick way                            |

| OPTION | DESCRIPTION   |
|--------|---|
|        | <p>of determining a successful connection before trying to open a socket with a device. The time-out of a connection with a socket can be very high. The available options are:</p> <ul style="list-style-type: none"> <li>• <b>Timeout:</b> Specify the number of milliseconds to wait for a reply from a <b>ping</b> command. Users must use a <b>ping</b> command to check the normal reply time, configuring this option for a value above that average. Usually this value can be configured between 1000 and 4000 milliseconds, that is, between 1 (one) and 4 (four) seconds</li> <li>• <b>Retries:</b> Number of retries of a <b>ping</b> command, not counting the first attempt. If all attempts fail, then the socket connection is aborted</li> </ul> |

**Available options on the Connect to group**

| OPTION                       | DESCRIPTION  |
|------------------------------|--|
| <b>Main IP</b>               | Type the IP address of a remote device. Users can use an IP address separated by dots, as well as a URL. In case of a URL, a Driver uses the available DNS service to map that URL to an IP address, such as "192.168.0.13" or "Server1" |
| <b>Port</b>                  | Type the IP port of a remote device, between 0 (zero) and 65535  |
| <b>Local port</b>            | Select this option to use a fixed local IP port when connecting to a remote device   |
| <b>Backup IP 1, 2, and 3</b> | Indicate the IP address, the IP port, and the fixed local IP port of up to 3 (three) backup addresses of a remote device   |

## General Configurations

This section contains information about the configuration of general **I/O Tags** and **Properties** of I/O Interfaces.

### I/O Tags

#### General I/O Interfaces Tags (N2/B2 = 0)

The Tags described next are provided for all supported I/O Interfaces.

#### IO.CommunicationStatus

|                             |                        |
|-----------------------------|------------------------|
| <b>Type of Tag</b>          | I/O Tag                |
| <b>Type of Access</b>       | Reading                |
| <b>N1 Parameter</b>         | -1 (minus one)         |
| <b>N2 Parameter</b>         | 0 (zero)               |
| <b>N3 Parameter</b>         | 0 (zero)               |
| <b>N4 Parameter</b>         | 6 (six)                |
| <b>String Configuration</b> | IO.CommunicationStatus |

This Tag informs the communication status of a Driver. It indicates how communication works relative to receiving valid data within a time period arbitrated in the configuration. For more information, please check topic **Setup Tab**. Possible values are **0 - Inactive communication**: The Driver did not receive valid data or stopped receiving data after *n* milliseconds, as configured in the properties window, or **1 - Active communication**: The Driver is receiving valid data.

## IO.IOKitEvent

|                           |                |
|---------------------------|----------------|
| <b>Type of Tag</b>        | Block Tag      |
| <b>Type of Access</b>     | Read-Only      |
| <b>B1 Parameter</b>       | -1 (minus one) |
| <b>B2 Parameter</b>       | 0 (zero)       |
| <b>B3 Parameter</b>       | 0 (zero)       |
| <b>B4 Parameter</b>       | 1 (one)        |
| <b>Size Property</b>      | 4 (four)       |
| <b>ParamItem Property</b> | IO.IOKitEvent  |

This Block returns Driver events generated by several sources in I/O Interfaces. The **TimeStamp** property of this Block represents the moment this event occurred. The Block Elements are the following:

- **Element 0**: Type of event. Possible values are **0**: Information, **1**: Warning, or **2**: Error
- **Element 1**: Source of an event. Possible values are **0**: Driver (specific of a Driver), **-1**: IOKit (generic events of I/O Interfaces), **-2**: **Serial** Interface, **-3**: **Modem** Interface, **-4**: **Ethernet** Interface, or **-5**: **RAS** Interface
- **Element 2**: Error number, specific for each source of event
- **Element 3**: Message of an event, a **String** specific for each event

### NOTE

A Driver keeps a maximum number of 100 events internally. If additional events are reported, older events are discarded.

## IO.PhysicalLayerStatus

|                             |                        |
|-----------------------------|------------------------|
| <b>Type of Tag</b>          | I/O Tag                |
| <b>Type of Access</b>       | Read-Only              |
| <b>N1 Parameter</b>         | -1 (minus one)         |
| <b>N2 Parameter</b>         | 0 (zero)               |
| <b>N3 Parameter</b>         | 0 (zero)               |
| <b>N4 Parameter</b>         | 2 (two)                |
| <b>String Configuration</b> | IO.PhysicalLayerStatus |

This Tag indicates the status of a physical layer. Possible values are the following:

- **0**: Physical layer stopped, that is, a Driver is in **Offline** mode, the physical layer failed when initializing, or exceeded the maximum number of reconnection attempts
- **1**: Physical layer started but not connected, that is, a Driver is in **Online** mode but the physical layer is not connected. If the **Connection management** option is configured with the value **Automatic**, the physical layer can be connecting, disconnecting, or waiting for a reconnection attempt. If the **Connection management** option is configured with the value **Manual**, then the physical layer remains in this status until forced to connect
- **2**: Physical layer connected, that is, the physical layer is ready for use. This **DOES NOT** mean a device is connected, only that the access layer is working

## IO.SetConfigurationParameters

|                           |                               |
|---------------------------|-------------------------------|
| <b>Type of Tag</b>        | Block Tag                     |
| <b>Type of Access</b>     | Read-Only                     |
| <b>B1 Parameter</b>       | -1 (minus one)                |
| <b>B2 Parameter</b>       | 0 (zero)                      |
| <b>B3 Parameter</b>       | 0 (zero)                      |
| <b>B4 Parameter</b>       | 3 (three)                     |
| <b>Size Property</b>      | 2 (two)                       |
| <b>ParamItem Property</b> | IO.SetConfigurationParameters |

Use this Tag to change any property of a Driver's configuration dialog box at run time.

This Tag works only while a Driver is in **Offline** mode. To start a Driver in **Offline** mode, select the **Start driver OFFLINE** option on that Driver's configuration dialog box. Users can write to a PLC Tag or to a Block Tag containing the parameters to change. Writing individual Block Elements is not supported, the whole Block must be written at once.

In **Eclipse SCADA**, users must use a Block Tag. Every parameter to configure uses two Block Elements. For example, if users want to configure 3 (three) parameters, then the size of the Block must be 6 (six,  $3 \times 2$ ). The first Element is the property's name, as a **String**, and the second Element is the property's value, according to the next example.

```
// 'Block' must be a Block Tag with automatic reading,
// scan reading, and automatic writings disabled.
// Configure all parameters
Block.element001 = "IO.Type" // Parameter 1
Block.element002 = "Serial"
Block.element003 = "IO.Serial.Port" // Parameter 2
Block.element004 = 1
Block.element005 = "IO.Serial.BaudRate" // Parameter 3
Block.element006 = 19200
// Writes the whole Block
Block.Write()
```

When using **Eclipse E3**, the ability to create arrays at run time allows using an I/O Tag as well as a Block Tag. Users can use the **Write** method of a Driver to send the parameters directly to that Driver, without creating a Tag, according to the next example.

```
Dim arr(6)
' Configure all array elements
arr(1) = "IO.Type"
arr(2) = "Serial"
arr(3) = "IO.Serial.Port"
arr(4) = 1
arr(5) = "IO.Serial.BaudRate"
arr(6) = 19200
' There are two methods to send parameters
' Method 1: Using an I/O Tag
tag.WriteEx arr
' Method 2: Without using a Tag
Driver.Write -1, 0, 0, 3, arr
```

A variation of the previous example uses a bidimensional array.

```
Dim arr(10)
' Configure all array elements. Notice the array was resized
' to 10 elements. Empty array elements are ignored by a Driver
arr(1) = Array("IO.Type", "Serial")
arr(2) = Array("IO.Serial.Port", 1)
arr(3) = Array("IO.Serial.BaudRate", 19200)
Driver.Write -1, 0, 0, 3, arr
```

A Driver does not validate parameter names or passed values, therefore be careful when writing parameters and values. The **Write** method fails if the configuration array is incorrectly created. Users can check the log of a Driver or use the *writeStatus* parameter of the **WriteEx** method to find out the exact cause of an error.

```
Dim arr(10), strError
arr(1) = Array("IO.Type", "Serial")
arr(2) = Array("IO.Serial.Port", 1)
arr(3) = Array("IO.Serial.BaudRate", 19200)
If Not Driver.WriteEx -1, 0, 0, 3, arr, , , strError Then
    MsgBox "Failed configuring Driver parameters: " + strError
End If
```

## IO.WorkOnline

|                             |                    |
|-----------------------------|--------------------|
| <b>Type of Tag</b>          | I/O Tag            |
| <b>Type of Access</b>       | Reading or Writing |
| <b>N1 Parameter</b>         | -1 (minus one)     |
| <b>N2 Parameter</b>         | 0 (zero)           |
| <b>N3 Parameter</b>         | 0 (zero)           |
| <b>N4 Parameter</b>         | 4 (four)           |
| <b>String Configuration</b> | IO.WorkOnline      |

This Tag informs the current status of a Driver and allows starting or stopping the physical layer. Possible values are the following:

- **0 - Driver Offline:** Physical layer is closed or stopped. This mode allows a dynamic configuration of a Driver's parameters using the **IO.SetConfigurationParameters** Tag
- **1 - Driver Online:** Physical layer is open or executing. While in **Online** mode, the physical layer can be connected or disconnected and its current status can be checked using the **IO.PhysicalLayerStatus** Tag

In the next example, using **Eclipse E3**, a Driver is configured to **Offline** mode, its COM port is changed, and then configured to **Online** mode again.

```
'Configure to Offline mode
Driver.Write -1, 0, 0, 4, 0
'Change port to COM2
Driver.Write -1, 0, 0, 3, Array("IO.Serial.Port", 2)
'Configure to Online mode
Driver.Write -1, 0, 0, 4, 1
```

The **Write** method may fail when configuring a Driver to **Online** mode, that is, writing the value 1 (one). In this case, this Driver remains in **Offline** mode. The cause of failure can be:

- Type of physical layer incorrectly configured, probably an invalid value was configured in the **IO.Type** property
- This Driver may have run out of memory
- Physical layer probably did not create its working thread. Search the log file for a message "Failed to create physical layer thread!"
- Physical layer could not start. The cause of this failure depends on the type of physical layer. It can be an invalid serial port number, a failure when starting Windows Sockets, or a failure when starting TAPI (modem), among others. This cause is recorded on the log file

#### IMPORTANT

Even if the configuration of a Driver to **Online** mode is successful, this does not necessarily mean the physical layer is ready to use, that is, ready to execute input and output operations with an external device. The **IO.PhysicalLayerStatus** Tag must be checked to ensure the physical layer is connected and ready for communication.

## Properties

These are general properties of all supported I/O Interfaces.

### IO.ConnectionMode

**9** Controls the management mode of a Connection. Possible values are **0**: Automatic mode, in which a Driver manages the connection or **1**: Manual mode, in which an application manages the connection.

### IO.GiveUpEnable

When configured to True, defines a maximum number of reconnection attempts. If all reconnection attempts fail, a Driver enters the **Offline** mode. When configured to False, a Driver tries until a reconnection is successful.

### IO.GiveUpTries

**9** Number of reconnection attempts before this one is aborted. For example, if the value of this property is equal to 1 (one), a Driver tries only one reconnection when the connection is lost. If this one fails, this Driver enters the **Offline** mode.

### IO.InactivityEnable

Configure to True to enable and to False to disable inactivity detection. The physical layer is disconnected if inactive for a certain period of time. The physical layer is considered inactive only if it is capable of sending data but not capable of receiving it back.

### IO.InactivityPeriodSec

**9** Number of seconds to check for inactivity. If the physical layer is inactive for this period of time, it is then disconnected.

## IO.RecoverEnable

☑ Configure to True to enable a Driver to recover lost connections and to False to leave a Driver in **Offline** mode when a connection is lost.

## IO.RecoverPeriodSec

9 Delay time between two connection attempts, in seconds.

### NOTE

The first reconnection is executed immediately after a connection is lost.

## IO.StartOffline

☑ Configure to True to start a Driver in **Offline** mode and to False to start a Driver in **Online** mode.

### NOTE

It is pointless to change this property at run time, as it can only be changed when a Driver is already in **Offline** mode. To configure a Driver in **Online** mode at run time, write the value 1 (one) to the **IO.WorkOnline** Tag.

## IO.TimeoutMs

9 Defines a time-out for the physical layer, in milliseconds. One second is equal to 1000 milliseconds.

## IO.Type

A Defines the type of physical interface used by a Driver. Possible values are the following:

- **N or None:** Does not use a physical interface, that is, a Driver must provide a customized interface
- **S or Serial:** Uses a local serial port (COM $n$ )
- **M or Modem:** Uses a local modem, internal or external, accessed via TAPI (*Telephony Application Programming Interface*)
- **E or Ethernet:** Uses a TCP/IP or UDP/IP socket
- **R or RAS:** Uses a **RAS** (*Remote Access Server*) Interface. A Driver connects to a RAS device using the **Ethernet** Interface and then sends an **AT** (*dial*) command

## Statistical Configuration

This section contains information about the configuration of **I/O Tags** and **Properties** of I/O Interfaces statistics.

### I/O Tags

#### Tags of I/O Interface Statistics (N2/B2 = 0)

The Tags described next display statistics for all I/O Interfaces.

## IO.Stats.Partial.BytesRecv

|                                |                            |
|--------------------------------|----------------------------|
| <b>Type of Tag</b>             | I/O Tag                    |
| <b>Type of Access</b>          | Read-Only                  |
| <b>N1 Parameter</b>            | -1 (minus one)             |
| <b>N2 Parameter</b>            | 0 (zero)                   |
| <b>N3 Parameter</b>            | 0 (zero)                   |
| <b>N4 Parameter</b>            | 1101                       |
| <b>Configuration by String</b> | IO.Stats.Partial.BytesRecv |

This Tag returns the number of bytes received in the current connection.

## IO.Stats.Partial.BytesSent

|                                |                            |
|--------------------------------|----------------------------|
| <b>Type of Tag</b>             | I/O Tag                    |
| <b>Type of Access</b>          | Read-Only                  |
| <b>N1 Parameter</b>            | -1 (minus one)             |
| <b>N2 Parameter</b>            | 0 (zero)                   |
| <b>N3 Parameter</b>            | 0 (zero)                   |
| <b>N4 Parameter</b>            | 1100                       |
| <b>Configuration by String</b> | IO.Stats.Partial.BytesSent |

This Tag returns the number of bytes sent through the current connection.

## IO.Stats.Partial.TimeConnectedSeconds

|                                |                                       |
|--------------------------------|---------------------------------------|
| <b>Type of Tag</b>             | I/O Tag                               |
| <b>Type of Access</b>          | Read-Only                             |
| <b>N1 Parameter</b>            | -1 (minus one)                        |
| <b>N2 Parameter</b>            | 0 (zero)                              |
| <b>N3 Parameter</b>            | 0 (zero)                              |
| <b>N4 Parameter</b>            | 1102                                  |
| <b>Configuration by String</b> | IO.Stats.Partial.TimeConnectedSeconds |

This Tag returns the number of seconds a Driver is connected in the current connection or 0 (zero) if a Driver is disconnected.

## IO.Stats.Partial.TimeDisconnectedSeconds

|                                |  |
|--------------------------------|--|
| <b>Type of Tag</b>             | I/O Tag                                  |
| <b>Type of Access</b>          | Read-Only                                |
| <b>N1 Parameter</b>            | -1 (minus one)                           |
| <b>N2 Parameter</b>            | 0 (zero)                                 |
| <b>N3 Parameter</b>            | 0 (zero)                                 |
| <b>N4 Parameter</b>            | 1103                                     |
| <b>Configuration by String</b> | IO.Stats.Partial.TimeDisconnectedSeconds |

This Tag returns the number of seconds a Driver is disconnected since the last connection ended or 0 (zero) if a Driver is connected.

## IO.Stats.Total.BytesRecv

|                                |                          |
|--------------------------------|--------------------------|
| <b>Type of Tag</b>             | I/O Tag                  |
| <b>Type of Access</b>          | Read-Only                |
| <b>N1 Parameter</b>            | -1 (minus one)           |
| <b>N2 Parameter</b>            | 0 (zero)                 |
| <b>N3 Parameter</b>            | 0 (zero)                 |
| <b>N4 Parameter</b>            | 1001                     |
| <b>Configuration by String</b> | IO.Stats.Total.BytesRecv |

This Tag returns the number of bytes received since a Driver was loaded.

## IO.Stats.Total.BytesSent

|                                |                          |
|--------------------------------|--------------------------|
| <b>Type of Tag</b>             | I/O Tag                  |
| <b>Type of Access</b>          | Read-Only                |
| <b>N1 Parameter</b>            | -1 (minus one)           |
| <b>N2 Parameter</b>            | 0 (zero)                 |
| <b>N3 Parameter</b>            | 0 (zero)                 |
| <b>N4 Parameter</b>            | 1000                     |
| <b>Configuration by String</b> | IO.Stats.Total.BytesSent |

This Tag returns the number of bytes sent since a Driver was loaded.

## IO.Stats.Total.ConnectionCount

|                                |                                |
|--------------------------------|--------------------------------|
| <b>Type of Tag</b>             | I/O Tag                        |
| <b>Type of Access</b>          | Read-Only                      |
| <b>N1 Parameter</b>            | -1 (minus one)                 |
| <b>N2 Parameter</b>            | 0 (zero)                       |
| <b>N3 Parameter</b>            | 0 (zero)                       |
| <b>N4 Parameter</b>            | 1004                           |
| <b>Configuration by String</b> | IO.Stats.Total.ConnectionCount |

This Tag returns the number of connections a Driver already established, successfully, since it was loaded.

## IO.Stats.Total.TimeConnectedSeconds

|                                |                                     |
|--------------------------------|-------------------------------------|
| <b>Type of Tag</b>             | I/O Tag                             |
| <b>Type of Access</b>          | Read-Only                           |
| <b>N1 Parameter</b>            | -1 (minus one)                      |
| <b>N2 Parameter</b>            | 0 (zero)                            |
| <b>N3 Parameter</b>            | 0 (zero)                            |
| <b>N4 Parameter</b>            | 1002                                |
| <b>Configuration by String</b> | IO.Stats.Total.TimeConnectedSeconds |

This Tag returns the number of seconds a Driver remained connected since it was loaded.

## IO.Stats.Total.TimeDisconnectedSeconds

|                                |  |
|--------------------------------|--|
| <b>Type of Tag</b>             | I/O Tag                                |
| <b>Type of Access</b>          | Read-Only                              |
| <b>N1 Parameter</b>            | -1 (minus one)                         |
| <b>N2 Parameter</b>            | 0 (zero)                               |
| <b>N3 Parameter</b>            | 0 (zero)                               |
| <b>N4 Parameter</b>            | 1003                                   |
| <b>Configuration by String</b> | IO.Stats.Total.TimeDisconnectedSeconds |

This Tag returns the number of seconds a Driver remained disconnected since it was loaded.

## Properties

Currently, there are no properties defined specifically to display I/O Interface statistics at run time.

# Ethernet Interface Configuration

This section contains information about the configuration of **I/O Tags** and **Properties** of an **Ethernet** Interface.

## I/O Tags

### Tags of an Ethernet Interface (N2/B2 = 4)

The Tags described next allow controlling and identifying an **Ethernet** Interface at run time and they are also valid when the **RAS** Interface is selected.

#### IMPORTANT

These Tags are available **ONLY** while a Driver is in **Online** mode.

### IO.Ethernet.IPSelect

|                             |                      |
|-----------------------------|----------------------|
| <b>Type of Tag</b>          | I/O Tag              |
| <b>Type of Access</b>       | Reading or Writing   |
| <b>N1 Parameter</b>         | -1 (minus one)       |
| <b>N2 Parameter</b>         | 0 (zero)             |
| <b>N3 Parameter</b>         | 4 (four)             |
| <b>N4 Parameter</b>         | 0 (zero)             |
| <b>String Configuration</b> | IO.Ethernet.IPSelect |

Indicates the active IP address. Possible values are **0**: The main IP address is selected, **1**: The first alternative or backup IP address is selected, **2**: The second alternative or backup IP address is selected, or **3**: The third alternative or backup IP address is selected.

If the **Ethernet** or **RAS** Interface is connected, this Tag indicates which one of the four configured IP addresses is in use. If the Interface is disconnected, this Tag indicates which IP address is used first on the next attempt to connect.

During the connection process, if the active IP address is not available, the I/O Interface tries to connect using the other IP address. If the connection with the alternative IP address works, it is configured as the active IP address (automatic switchover).

To force a manual switchover, write values from 0 (zero) to 3 (three) to this Tag. This forces a reconnection with the specified IP address (**0**: Main address or **1, 2, 3**: Alternative address) if a Driver is currently connected. If a Driver is disconnected, this Tag configures the active IP address for the next attempt to connect.

## IO.Ethernet.IPSwitch

|                             |                      |
|-----------------------------|----------------------|
| <b>Type of Tag</b>          | I/O Tag              |
| <b>Type of Access</b>       | Write-Only           |
| <b>N1 Parameter</b>         | -1 (minus one)       |
| <b>N2 Parameter</b>         | 0 (zero)             |
| <b>N3 Parameter</b>         | 4 (four)             |
| <b>N4 Parameter</b>         | 1 (one)              |
| <b>String Configuration</b> | IO.Ethernet.IPSwitch |

Any value written to this Tag forces a manual switchover. If the main IP address is active, then the first alternative or backup IP address is activated, and so on for all alternative IP addresses and returning to the main address until a connection is established.

If a Driver is disconnected, this Tag configures the active IP address for the next attempt to connect.

## IO.Ethernet.SocketState

|                             |                         |
|-----------------------------|-------------------------|
| <b>Type of Tag</b>          | I/O Tag                 |
| <b>Type of Access</b>       | Read-Only               |
| <b>N1 Parameter</b>         | -1 (minus one)          |
| <b>N2 Parameter</b>         | 0 (zero)                |
| <b>N3 Parameter</b>         | 4 (four)                |
| <b>N4 Parameter</b>         | 2 (two)                 |
| <b>String Configuration</b> | IO.Ethernet.SocketState |

The Value property of this Tag corresponds to socket states as a map of bits:

- **Bit 0:** 0 (zero, not listening) or 1 (one, listening)
- **Bit 1:** 0 (zero, disconnected) or 1 (one, connected)

## Properties

These properties control the configuration of an **Ethernet** Interface.

### NOTE

The **Ethernet** Interface is also used by the **RAS** Interface.

## IO.Ethernet.AcceptConnection

Configure to False if a Driver must not accept external connections, that is, if a Driver behaves as a master, or configure to True to enable the reception of connections, that is, if a Driver behaves as a slave.

## IO.Ethernet.BackupEnable[2,3]

■ Configure to True to enable an alternative or backup IP address. If the reconnection attempt with the main IP address fails, a Driver tries to use an alternative IP address. Configure to False to disable its usage.

## IO.Ethernet.BackupIP[2,3]

▲ Alternative or backup IP address of a remote device. Users can use a numerical address, as well as a device's host name, such as "192.168.0.7" or "SERVER2".

## IO.Ethernet.BackupLocalPort[2,3]

9 Local port number to be used when connecting to an alternative IP address of a remote device. Used only if **IO.Ethernet.BackupLocalPortEnable** is equal to True.

## IO.Ethernet.BackupLocalPortEnable[2,3]

■ Configure to True to force the use of a specific local port when connecting to an alternative or backup IP address or configure to False to use any available local port.

## IO.Ethernet.BackupPort[2,3]

9 Port number of an alternative or backup IP address of a remote device, used with the **IO.Ethernet.BackupIP** property.

## IO.Ethernet.IPFilter

▲ List with a comma-separated IPv4 or IPv6 addresses, which defines from which addresses a Driver accepts or blocks connections. Users can use asterisks, such as "192.168.\*.\*", or intervals, such as "192.168.0.41-50", in any part of IP addresses. To block an IP address or a range of IP addresses, use the tilde ("~") character at the beginning of the address, according to the next examples:

- **192.168.0.24**: Accepts only connections from IPv4 address 192.168.0.24
- **192.168.0.41-50**: Accepts connections from IPv4 addresses in the interval between 192.168.0.41 and 192.168.0.50
- **192.168.0.\***: Accepts connections from IPv4 addresses in the interval between 192.168.0.0 and 192.168.0.255
- **fe80:3bf:877::\*:\* (expands to fe80:03bf:0877:0000:0000:0000:0000:0000:\*)**: Accepts connections from IPv6 addresses in the interval between fe80:03bf:0877:0000:0000:0000:0000:0000 and fe80:03bf:0877:0000:0000:0000:ffff:ffff
- **192.168.0.10, 192.168.0.15, 192.168.0.20**: Accepts connections from IPv4 addresses 192.168.0.10, 192.168.0.15, and 192.168.0.20
- **~192.168.0.95, 192.168.0.\***: Accepts connections from IPv4 addresses in the interval between 192.168.0.0 and 192.168.0.255, except the IPv4 address 192.168.0.95

When a Driver receives a connection attempt, the list of filters is scanned sequentially from left to right, searching for a specific authorization or block for the IP address where the connection comes from. If no element on the list corresponds to the IP address, the authorization or block are dictated by the last element of that list:

- If the last element on the list is an authorization, such as "192.168.0.24", then all IP addresses not found on the list are blocked
- If the last element on the list is a block, such as "~192.168.0.24", then all IP addresses not found on the list are authorized

If an IP address appears on more than one filter on the list, the leftmost filter has precedence. For example, in case of "~192.168.0.95, 192.168.0.\*", the IP address 192.168.0.95 fits both rules, but the rule that wins is the leftmost one, "~192.168.0.95", and therefore this IP address is blocked.

When **IOKit** blocks a connection, it logs a message "Blocked incoming socket connection from {IP}!".

In case of UDP connections in broadcast listening mode, in which a Driver can receive packets from different IP addresses, blocks or permissions are performed at each packet received. If a packet is received from a blocked IP address, it logs a message "Blocked incoming packet from {IP} (discarding {N} bytes)!".

## IO.Ethernet.ListenIP

**A** IP address of the local network interface that a Driver uses to establish and accept connections. Leave this property empty to establish and accepts connections using any local network interface.

## IO.Ethernet.ListenPort

**9** Number of the IP port used by a Driver to listen to connections.

## IO.Ethernet.MainIP

**A** IP address of a remote device. Users can use a numerical address, as well as a device's host name, such as "192.168.0.7" or "SERVER2".

## IO.Ethernet.MainLocalPort

**9** Local port number to use when connecting to the main IP address of a remote device. This value is only used if the **IO.Ethernet.MainLocalPortEnable** property is equal to True.

## IO.Ethernet.MainLocalPortEnable

**☑** Configure to True to force the use of a specific local port when connecting to the main IP address of a remote device or configure to False to use any available local port.

## IO.Ethernet.MainPort

**9** Number of the IP port of a remote device, used with the **IO.Ethernet.MainIP** property.

## IO.Ethernet.PingEnable

**☑** Configure to True to enable sending a **ping** command to the IP address of a remote device, before trying to connect to the socket. This socket's connection time-out cannot be controlled, therefore sending a **ping** command before connecting is a fast way to detect if the connection is going to fail. Configure to False to disable a **ping** command.

## IO.Ethernet.PingTimeoutMs

**9** Delay time to wait for a response from a **ping** command, in milliseconds.

## IO.Ethernet.PingTries

**9** Maximum number of attempts of a **ping** command. Minimum value is 1 (one), including the first **ping** command.

## IO.Ethernet.ShareListenPort

☑ Configure to True to share a listening port with other Drivers and processes or False to open a listening port in exclusive mode. To successfully share a listening port, all Drivers and processes that use that port must open it in shared mode. When a listening port is shared, each incoming connection is distributed to one of the processes listening. This way, if a Slave Driver only supports one connection at a time, users can use several instances of this Driver listening on the same port, therefore simulating a Driver with support for multiple connections.

## IO.Ethernet.SupressEcho

☑ Configure to True to eliminate echoes in communication. An echo is the unwanted reception of an exact copy of all data packets a Driver sent to a device.

## IO.Ethernet.Transport

⚠ Defines a transport protocol. Possible values are **T or TCP**: Uses the TCP/IP protocol or **U or UDP**: Uses the UDP/IP protocol.

## IO.Ethernet.UseIPv6

☑ Configure to True to use IPv6 addresses on all Ethernet connections or configure to False to use IPv4 addresses (default).

## Driver Revision History

| VERSION | DATE       | AUTHOR      | COMMENTS  |
|---------|------------|-------------|---|
| 1.0.3   | 09/04/2025 | M. Ludwig   | <ul style="list-style-type: none"> <li>• Driver updated to <b>IOKit</b> library version <b>3.0</b> and Visual Studio 2022 (<i>Case 37925</i>).</li> <li>• Added a protection identifier to this Driver (<i>Case 38113</i>).</li> <li>• Added a limitation on the number of connections per Driver (<i>Case 38114</i>).</li> </ul> |
| 1.0.1   | 12/01/2023 | M. Salvador | <ul style="list-style-type: none"> <li>• Initial version of this Driver.</li> </ul>   |

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